

# NAG Fortran Library Routine Document

## **F02GJF**

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

### 1 Purpose

F02GJF calculates all the eigenvalues and, if required, all the eigenvectors of the complex generalized eigenproblem  $Ax = \lambda Bx$  where  $A$  and  $B$  are complex, square matrices, using the *QZ* algorithm.

### 2 Specification

```
SUBROUTINE F02GJF (N, AR, IAR, AI, IAI, BR, IBR, BI, IBI, EPS1, ALFR,
1                      ALFI, BETA, MATV, VR, IVR, VI, IVI, ITER, IFAIL)

INTEGER
double precision
1                      N, IAR, IAI, IBR, IBI, IVR, IVI, ITER(N), IFAIL
AR(IAR,N), AI(IAI,N), BR(IBR,N), BI(IBI,N), EPS1,
1                      ALFR(N), ALFI(N), BETA(N), VR(IVR,N), VI(IVI,N)
LOGICAL
1                      MATV
```

### 3 Description

All the eigenvalues and, if required, all the eigenvectors of the complex generalized eigenproblem  $Ax = \lambda Bx$  where  $A$  and  $B$  are complex, square matrices, are determined using the *QZ* algorithm. The complex *QZ* algorithm consists of three stages:

1.  $A$  is reduced to upper Hessenberg form (with real, non-negative subdiagonal elements) and at the same time  $B$  is reduced to upper triangular form.
2.  $A$  is further reduced to triangular form while the triangular form of  $B$  is maintained and the diagonal elements of  $B$  are made real and non-negative.

F02GJF does not actually produce the eigenvalues  $\lambda_j$ , but instead returns  $\alpha_j$  and  $\beta_j$  such that

$$\lambda_j = \alpha_j / \beta_j, \quad j = 1, 2, \dots, n.$$

The division by  $\beta_j$  becomes the responsibility of your program, since  $\beta_j$  may be zero, indicating an infinite eigenvalue.

3. If the eigenvectors are required ( $MATV = .TRUE.$ ), they are obtained from the triangular matrices and then transferred back into the original co-ordinate system.

### 4 References

Moler C B and Stewart G W (1973) An algorithm for generalized matrix eigenproblems *SIAM J. Numer. Anal.* **10** 241–256

Ward R C (1975) The combination shift *QZ* algorithm *SIAM J. Numer. Anal.* **12** 835–853

Wilkinson J H (1979) Kronecker's canonical form and the *QZ* algorithm *Linear Algebra Appl.* **28** 285–303

### 5 Parameters

- 1:  $N$  – INTEGER *Input*  
*On entry:*  $n$ , the order of the matrices  $A$  and  $B$ .  
*Constraint:*  $N \geq 1$ .

2: AR(IAR,N) – ***double precision*** array *Input/Output*

*On entry:* the real parts of the elements of the  $n$  by  $n$  complex matrix  $A$ .

*On exit:* the array is overwritten.

3: IAR – INTEGER *Input*

*On entry:* the first dimension of the array AR as declared in the (sub)program from which F02GJF is called.

*Constraint:*  $IAR \geq N$ .

4: AI(IAI,N) – ***double precision*** array *Input/Output*

*On entry:* the imaginary parts of the elements of the  $n$  by  $n$  complex matrix  $A$ .

*On exit:* the array is overwritten.

5: IAI – INTEGER *Input*

*On entry:* the first dimension of the array AI as declared in the (sub)program from which F02GJF is called.

*Constraint:*  $IAI \geq N$ .

6: BR(IBR,N) – ***double precision*** array *Input/Output*

*On entry:* the real parts of the elements of the  $n$  by  $n$  complex matrix  $B$ .

*On exit:* the array is overwritten.

7: IBR – INTEGER *Input*

*On entry:* the first dimension of the array BR as declared in the (sub)program from which F02GJF is called.

*Constraint:*  $IBR \geq N$ .

8: BI(IBI,N) – ***double precision*** array *Input/Output*

*On entry:* the imaginary parts of the elements of the  $n$  by  $n$  complex matrix  $B$ .

*On exit:* the array is overwritten.

9: IBI – INTEGER *Input*

*On entry:* the first dimension of the array BI as declared in the (sub)program from which F02GJF is called.

*Constraint:*  $IBI \geq N$ .

10: EPS1 – ***double precision*** *Input*

*On entry:* a tolerance used to determine negligible elements.

$\text{EPS1} > 0.0$

An element will be considered negligible if it is less than EPS1 times the norm of its matrix.

$\text{EPS1} \leq 0.0$

***machine precision*** is used for EPS1.

A positive value of EPS1 may result in faster execution but less accurate results.

11: ALFR(N) – ***double precision*** array *Output*

12: ALFI(N) – ***double precision*** array *Output*

*On exit:* the real and imaginary parts of  $\alpha_j$ , for  $j = 1, 2, \dots, n$ .

13:	BETA(N) – <b>double precision</b> array	<i>Output</i>
	<i>On exit:</i> $\beta_j$ , for $j = 1, 2, \dots, n$ .	
14:	MATV – LOGICAL	<i>Input</i>
	<i>On entry:</i> must be set .TRUE. if the eigenvectors are required, otherwise .FALSE..	
15:	VR(IVR,N) – <b>double precision</b> array	<i>Output</i>
	<i>On exit:</i> if MATV = .TRUE., the $j$ th column of VR contains the real parts of the eigenvector corresponding to the $j$ th eigenvalue. The eigenvectors are normalized so that the sum of squares of the moduli of the components is equal to 1.0 and the component of largest modulus is real.	
	If MATV = .FALSE., VR is not used.	
16:	IVR – INTEGER	<i>Input</i>
	<i>On entry:</i> the first dimension of the array VR as declared in the (sub)program from which F02GJF is called.	
	<i>Constraint:</i> $IVR \geq N$ .	
17:	VI(IVI,N) – <b>double precision</b> array	<i>Output</i>
	<i>On exit:</i> if MATV = .TRUE., the $j$ th column of VI contains the imaginary parts of the eigenvector corresponding to the $j$ th eigenvalue.	
	If MATV = .FALSE., VI is not used.	
18:	IVI – INTEGER	<i>Input</i>
	<i>On entry:</i> the first dimension of the array VI as declared in the (sub)program from which F02GJF is called.	
	<i>Constraint:</i> $IVI \geq N$ .	
19:	ITER(N) – INTEGER array	<i>Output</i>
	<i>On exit:</i> ITER( $j$ ) contains the number of iterations needed to obtain the $j$ th eigenvalue. Note that the eigenvalues are obtained in reverse order, starting with the $n$ th.	
20:	IFAIL – INTEGER	<i>Input/Output</i>
	<i>On entry:</i> IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Chapter P01 for details.	
	<i>On exit:</i> IFAIL = 0 unless the routine detects an error (see Section 6).	
	For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter the recommended value is 0. <b>When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.</b>	

## 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL =  $i$

More than  $30 \times N$  iterations have been performed altogether in the second step of the *QZ* algorithm; IFAIL is set to the index  $i$  of the eigenvalue at which the failure occurs. On soft failure,  $\alpha_j$  and  $\beta_j$

are correct for  $j = i + 1, i + 2, \dots, n$ , but the arrays VR and VI do not contain any correct eigenvectors.

## 7 Accuracy

The computed eigenvalues are always exact for a problem  $(A + E)x = \lambda(B + F)x$  where  $\|E\|/\|A\|$  and  $\|F\|/\|B\|$  are both of the order of  $\max(\text{EPS1}, \epsilon)$ , EPS1 being defined as in Section 5 and  $\epsilon$  being the *machine precision*.

**Note:** interpretation of results obtained with the QZ algorithm often requires a clear understanding of the effects of small changes in the original data. These effects are reviewed in Wilkinson (1979), in relation to the significance of small values of  $\alpha_j$  and  $\beta_j$ . It should be noted that if  $\alpha_j$  and  $\beta_j$  are **both** small for any  $j$ , it may be that no reliance can be placed on **any** of the computed eigenvalues  $\lambda_i = \alpha_i/\beta_i$ . You are recommended to study Wilkinson (1979) and, if in difficulty, to seek expert advice on determining the sensitivity of the eigenvalues to perturbations in the data.

## 8 Further Comments

The time taken by F02GJF is approximately proportional to  $n^3$  and also depends on the value chosen for parameter EPS1.

## 9 Example

To find all the eigenvalues and eigenvectors of  $Ax = \lambda Bx$  where

$$A = \begin{pmatrix} -21.10 - 22.50i & 53.5 - 50.5i & -34.5 + 127.5i & 7.5 + 0.5i \\ -0.46 - 7.78i & -3.5 - 37.5i & -15.5 + 58.5i & -10.5 - 1.5i \\ 4.30 - 5.50i & 39.7 - 17.1i & -68.5 + 12.5i & -7.5 - 3.5i \\ 5.50 + 4.40i & 14.4 + 43.3i & -32.5 - 46.0i & -19.0 - 32.5i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1.0 - 5.0i & 1.6 + 1.2i & -3.0 & -1.0i \\ 0.8 - 0.6i & 3.0 - 5.0i & -4.0 + 3.0i & -2.4 - 3.2i \\ 1.0 & 2.4 + 1.8i & -4.0 - 5.0i & -3.0i \\ 1.0i & -1.8 + 2.4i & 0.0 - 4.0i & 4.0 - 5.0i \end{pmatrix}.$$

### 9.1 Program Text

```

*      F02GJF Example Program Text
*      Mark 14 Revised. NAG Copyright 1989.
*      .. Parameters ..
  INTEGER          NMAX, IAR, IAI, IBR, IBI, IVR, IVI
  PARAMETER        (NMAX=4, IAR=NMAX, IAI=NMAX, IBR=NMAX, IBI=NMAX,
+                  IVR=NMAX, IVI=NMAX)
  INTEGER          NIN, NOUT
  PARAMETER        (NIN=5, NOUT=6)
*      .. Local Scalars ..
  DOUBLE PRECISION EPS1
  INTEGER          I, IFAIL, J, N
  LOGICAL          MATV
*      .. Local Arrays ..
  DOUBLE PRECISION AI(IAI,NMAX), ALFI(NMAX), ALFR(NMAX),
+                  AR(IAR,NMAX), BETA(NMAX), BI(IBI,NMAX),
+                  BR(IBR,NMAX), VI(IVI,NMAX), VR(IVR,NMAX)
  INTEGER          ITER(NMAX)
*      .. External Functions ..
  DOUBLE PRECISION X02AJF
  EXTERNAL         X02AJF
*      .. External Subroutines ..
  EXTERNAL         F02GJF
*      .. Executable Statements ..
  WRITE (NOUT,*) 'F02GJF Example Program Results'
*      Skip heading in data file

```

```

READ  (NIN,*) 
READ  (NIN,*) N
IF (N.GT.0 .AND. N.LE.NMAX) THEN
    READ (NIN,*) ((AR(I,J),AI(I,J),J=1,N),I=1,N)
    READ (NIN,*) ((BR(I,J),BI(I,J),J=1,N),I=1,N)
    EPS1 = X02AJF()
    MATV = .TRUE.
    IFAIL = 1
*
    CALL F02GJF(N,AR,IAR,AI,IAI,BR,IBR,BI,IBI,EPS1,ALFR,ALFI,BETA,
+                  MATV,VR,IVR,VI,IVI,ITER,IFAIL)
*
    WRITE (NOUT,*)
    IF (IFAIL.NE.0) THEN
        WRITE (NOUT,99999) 'Error in F02GJF. IFAIL =', IFAIL
    ELSE
        DO 20 I = 1, N
            ALFR(I) = ALFR(I)/BETA(I)
            ALFI(I) = ALFI(I)/BETA(I)
20      CONTINUE
        WRITE (NOUT,*) 'Eigenvalues'
        WRITE (NOUT,99998) (' (',ALFR(I),',',ALFI(I),')',I=1,N)
        WRITE (NOUT,*) 'Eigenvectors'
        DO 40 I = 1, N
            WRITE (NOUT,99998) (' (',VR(I,J),',',VI(I,J),')',J=1,N)
40      CONTINUE
        END IF
    ELSE
        WRITE (NOUT,99999) 'N is out of range: N = ', N
    END IF
    STOP
*
99999 FORMAT (1X,A,I5)
99998 FORMAT (1X,4(A,F7.3,A,F7.3,A))
END

```

## 9.2 Program Data

F02GJF Example Program Data

```

4
-21.10 -22.50  53.50 -50.50 -34.50 127.50   7.50   0.50
-0.46  -7.78  -3.50 -37.50 -15.50  58.50 -10.50 -1.50
 4.30  -5.50  39.70 -17.10 -68.50  12.50 -7.50 -3.50
 5.50   4.40  14.40  43.30 -32.50 -46.00 -19.00 -32.50
 1.00  -5.00   1.60   1.20  -3.00   0.00   0.00  -1.00
 0.80  -0.60   3.00  -5.00  -4.00   3.00  -2.40  -3.20
 1.00   0.00   2.40   1.80  -4.00  -5.00   0.00  -3.00
 0.00   1.00  -1.80   2.40   0.00  -4.00   4.00  -5.00

```

## 9.3 Program Results

F02GJF Example Program Results

Eigenvalues

```

( 3.000, -9.000) ( 2.000, -5.000) ( 3.000, -1.000) ( 4.000, -5.000)

```

Eigenvectors

```

( 0.945,  0.000) ( 0.996,  0.000) ( 0.945,  0.000) ( 0.988,  0.000)
( 0.151, -0.113) ( 0.005, -0.003) ( 0.151, -0.113) ( 0.009, -0.007)
( 0.113,  0.151) ( 0.063, -0.000) ( 0.113, -0.151) ( -0.033,  0.000)
( -0.151,  0.113) ( 0.000,  0.063) ( 0.151,  0.113) ( 0.000,  0.154)

```

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